

AUBO-i16

Collaborative Lightweight Robot



6 axis 16Kg payload 967.5 mm reach











Collaborative Robot (Co-Bot)

AUBO Robots work closely within the human environment without the need for safety equipment, depending on risk assessment.

COLLABORATIVE FUNCTION:

- Hand guide-to-teach (inverse kinematics motion planning), this manual operation of the robot enables quick and easy programming by demonstration without any programming skills.
- Robot works side by side with human operator without safety fence, laser or sensors (after a risk assessment is performed).
- Teach pendant user interface for programing (forward kinematics) enables online programming and simulation via a touch screen tablet.
- Lightweight, flexible and easy to re-purpose this lightweight robot.

SAFETY FUNCTIONS:

- Designed in accordance with PI d and ISO 10218-1 (ISO/TS 15066) safety requirements and with most all specifications for collaborative robots operation.
- Power and force limiting design brings robot to a protective stop if limits are exceeded or a collision is detected.
 Speed and force can be adjusted to fit and optimize any application easily.
- Sensors embedded in motor drives provide real-time feedback to prevent dangerous situations.
- Emergency stop buttons are positioned on teach pendant and control box with a braking distance less than 1mm.

OPEN SOURCE ARCHITECTURE:

- CAN bus network used in this robot for multiple microcontrollers to communicate with each other.
- ROS (Robot Operating System) compatibility is supported through an API.
- Hardware adopts BUS protocols with open I/O interface extensions.
- Easily integrate robot into existing production systems.

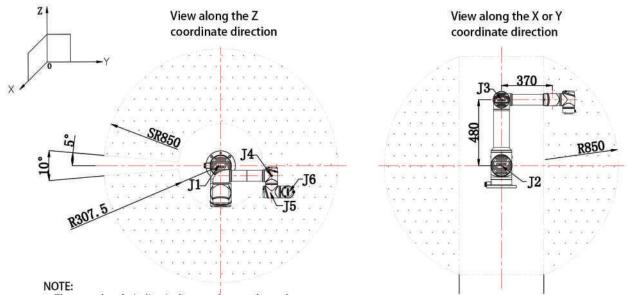
RETURN ON INVESTMENT (ROI):

- Low cost of ownership without basic programing skills needed, and ease of integration into a system, all add up to a quick return on your investment.
- Short run, high mix environments like Lab automation or machine tending are prime examples of industries needing fast redeployment.
- Floor space is a premium cost at most companies—usually more than the equipment. A small foot print, lightweight robot will be a huge benefit for any size company's cost of production.
- Repurpose, redeploy and/or reinvent applications with the same robot, fast change over for lean manufacturing.
- Remove human error in a high-mix low-volume (HMLV), this reduces manufacturing time and consequently increases capacity; without adding costly resources so robot acts as a de facto quality inspector.

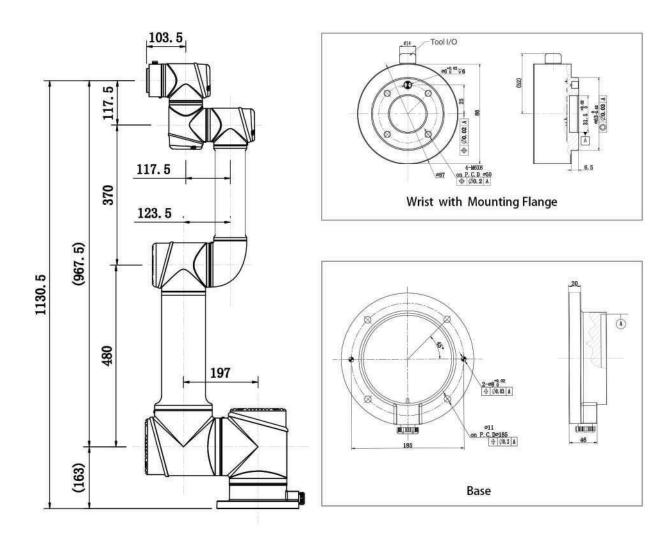
INTELLIGENCE:

- Vison systems can be easily integrated into controller.
- Control Box communication ports include TCP/IP, Modbus RTU/TCP, and USB 2.0
- This research robot platform is used widely around the world in corporate labs and for academic robotics research.

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- 1. The two-dot chain line indicates: the area boundary
- 2. The space area enclosed by the double-dot-dash line is the area where the robot arm is mounted, and the hoisting and vertical installation suggest the area of the tool end trajectory when the robot arm works best
- 3. The limit trajectory of the tool end movement of the robotic arm may exceed the area enclosed by the two-dot chain line
- 4. The double-dot-dash-contained space region is the intersection of the space region contained on the inner surface of a defective sphere and the space region on the outer surface of a cylinder.



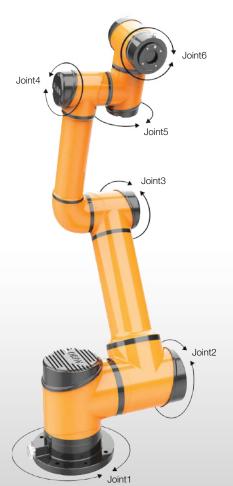






AUB0-116

6 axis 16 Kg payload 967,5mm reach







ROBOT SPECIFICATIONS

 Degrees of Freedom
 6 axes

 Reach
 967.5 mm

 Payload
 16 Kg

 Weight
 38 Kg

Dimensions 1183x420x218 mm

Collaboration Collaborative operation according to ISO 10218-1 :2001

Repeatability +/- 0.1 mm Linear Velocity $\leq 4.0 \text{ m/s}$

Power Consumption 500 W (under normal working conditions)

Materials Aluminum, Steel, Plastic

Ambient Humidity

Ambient Temperature

IP Classification

Aluminum,
25% - 90%
0 - 50° C
IP54

Programming Teach pendant with user interface

Mounting Surface Diameter

Motor Type

DC 48 ∨

Installation Orientation Any Ceiling, Floor, Wall

WORKING MAXIMUM AXIS MOVEMENT RANGE SPEED J1 axis rotation base (+/-) 175° 180°/sec J2 axis rotation shoulder (+/-) 175° 180°/sec J3 axis rotation elbow 267°/sec (+/-) 175° J4 axis wrist rotation $(+/-) 175^{\circ}$ 180°/sec

I/O PORT ON WRIST

Voltage	Current	Digital In	Digital out	Analog In	Analog Out
0/12/24 V	0.8 A	4	4	2	0

(+/-) 175°

 $(+/-) 175^{\circ}$

180°/sec

180°/sec

CONTROL BOX

J5 axis wrist swing

J6 axis wrist rotation

Dimensions (LxWxH) 380x350x265 mm

Weight 15 Kg
Cabling 5 m (customizable, up to 8m)
Color Black

Communication Ethernet, Modbus - RTU/TCP,Profinet (Optional)

Interface SDK (supports C/C++/Lua/Python) Supports ROS, API

Power supply 100 - 240 VAC, 50 - 60 Hz

IP Classification IP43

I/O PORTS General I/O Safety I/O Digital in 16 16

 Digital out
 16
 16

 Analog In
 4

 Analog out
 4

 Output Voltage
 24 V

 Output Current
 3 A Max

TEACH PENDANT

 Dimensions (LxWxH)
 355x235x54 mm

 Weight
 1.57 Kg

Display Screen 30 cm Touch LCD Screen
Cabling 4 m

Cabling 4 m
IP Classification IP43
Color Oran



About Aubo Robotics

Aubo Robotics was established in collaboration between professors from the USA and China to make a lightweight intelligent collaborative robot. This robot arm was specially designed with important functions from the start, combining state of the art technology with user friendliness to make this a collaborative robot (Co-bot). The open source architecture enables the Robot Operating System (ROS) to be supported through an API for both industrial and academic uses.

The Aubo i Series of robots use the CAN bus networks to communicate between joints. Low cost of ownership and high positional repeatability are some of the other criteria that makes up the outstanding features of this robot. Aubo Robotics holds several core patents and has strategic cooperation with several public companies leveraging the best of all new technologies.

Robotic automation is no longer out of range for small to midsize companies. The user-friendly setup facilitates ROI in real production environments so employees without programming skills can adapt these robots for most high mix or small batch applications. Aubo looks forward to helping companies make use of this new technology and gain competitive advantage in manufacturing environment while reducing the dangerous and repetitive tasks performed by workers today.

Some places where you may see AUBO Robots:

Assembly, Packaging, Welding, Pick and Place, Inspection, Machine Tending, Pharmaceutical and Medical Labs, Research and Development, and Academia.





Applications for Collaborative Robots



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